

Day Ahead Solar Pv Power Forecasting Based On A Combination Of Statistical And Physical Modelling Utilizing Nwp Data For Solar Parks In India

Arindam Roy
NIWE

Aravindakshan Ramanan
GIZ GmbH

Barun Kumar
NIWE

Naveen Kumar
NIWE

Chris Alice Abraham
NIWE

Anette Hammer
Univ of Oldenburg

Elena Barykina
Overspeed GmbH

Detlev Heinemann
Univ of Oldenburg

Hans Peter Waldl
Overspeed GmbH

Indradip Mitra
GIZ GmbH

Prasun Kumar Das
NIWE

Karthik Ramanathan
NIWE

Balaraman Kannan
NIWE

Abstract— This paper attempts to develop appropriate models for solar power prediction for large MW scale Solar PV park in India. Focus is laid on Solar power prediction of large MW scale PV plant in India with hybrid approach of physical and statistical models. The objective of the exercise is to develop day ahead forecasts of 15 minutes temporal resolution and meet the current regulatory requirements in India mandated by Central Electricity Regulatory Commission. The hybrid method considers physical model supported by NWP data sets and plant specific measurement of irradiation along with Artificial Neural Network and other statistical techniques for bias correction of irradiance and AC power. As input data is critical in physical model, an appropriate filtering techniques on data quality has been carried out. As the Numerical Weather Prediction from NWP is available for every 3 hours/ 1 hours, necessary post processing to interpolate it to 15 minutes time resolution has been carried out. Ground based irradiation measurements was utilized for site specific bias correction. Two different bias correction approaches were cross-compared. The present approach considers Chandrasekhar Diffuse fraction model coupled with Klucher model to convert from irradiation on horizontal plane to panel tilt. For estimation of DC power output from solar PV panel, Huld and Beyer model are considered. Inverter characteristics are modelled using Schmidt Sauer model. These models are tested for various NWP data sets and their statistical combination. The results are validated against actual power output from plant and analysed in the form of NRMSE, NMAE for each 15 minutes time block. It is observed that accuracy of the model is directly dependant on availability of detailed information and data from the plant. It also seen that forecasting in general is within the deviation limits prescribed by regulatory authorities.

Keywords- Solar forecasting, Day ahead, physical, statistical, India

I. INTRODUCTION

The Government has set an ambitious target of 100 GW of grid-connected solar power by the year 2021-22 under the National Solar Mission. The installed capacity of grid connected wind power plants is 34.98 GW and for solar power plants is 24.31 GW [33].

The large scale integration of these renewable sources poses to be a challenge to the grid operators for balancing the demand and generation. In order to maintain grid security, essential measures need to be taken to manage the variability of renewable generation. Forecasting is very essential information for the grid operator which will help in maintain the stability of grid.

In order to align and cater to the needs of current situation, indigenous forecasting model chain was developed. Few large scale solar power plants co-located was considered as test case for solar power forecasting model development. Model was developed considering the system as a single large size solar power plant. The model chain was mixture of physical and statistical approaches. Scientific approach was followed to develop location specific coefficients for solar forecasting model chain. Indigenous data sets namely measured data from Solar power plant, Numerical Weather Prediction models from National Centre for Medium Range Weather Forecasting, etc was employed.

II. LITERATURE REVIEW

The forecasting model chain consist of converting the irradiance prediction from NWP into tilted radiation and finally combining it with the model of solar PV power plant .Methodology for solar power forecasting is represented in Figure 2. Detailed explanation of the methodology followed in this work is provided in the subsequent section. In this section, different alternative techniques found in the literature for various blocks in solar forecasting model chain is explained.

A. Bias Correction of Numerical Weather Prediction Models

The numerical weather prediction models have a coarse resolution spanning a large area. Therefore, bias following a specific pattern could be identified when it is compared with site specific measurements. There are some methods in the literature through which this bias could be modelled and reduced from forecasts. Some of the methods are detailed in as following:

1) Bias as a standard bi-variate 4th order polynomial function of the cosine of Solar Zenith angle and Clear Sky Index

The bias could be modelled as a standard bi-variate 4th order polynomial function of the cosine of Solar Zenith angle and Clear Sky Index. Based on NWP forecasts for a particular location and corresponding measured GHI data, the values of coefficients could be estimated by curve fitting equation.

2) Bias as a binned function of the cosine of Solar Zenith Angle and Clear Sky Index

Bias is defined as a binned function of the cosine of Solar Zenith Angle and Clear Sky Index. A user defined 2D bin is created with one edge of sequentially increasing values of k_t^* from 0 till 1 with user defined interval size and other edge specified by increasing values of $(\cos \theta_z)$ [1,2]. The bins are represented in Figure 1. The average bias is calculated for each of the bins in the historical data set. Therefore, for the validation period, bias is assigned to the forecasts based on the bin it represents. The requirement for this method to work accurately is to have large training data set (minimum of one year of data).

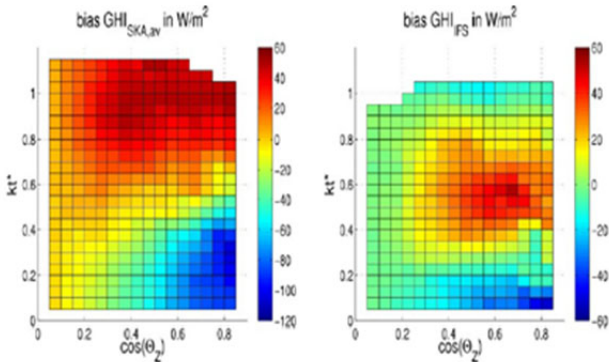


Figure 1:Representation of Binned bias as function of clear-sky index and cosine of zenith angle [2]

3) Bias as the output of a Feed-forward Neural Network with hidden layers and two inputs – cosine of Solar Zenith angle and Clear Sky Index

Bias could be modelled as output of a Feed-forward Neural Network with hidden layers and two inputs – cosine of Solar Zenith angle and Clear Sky Index [3]. On the process of training with historical dataset of Numerical Weather prediction models and ground measured data set, weights and offsets of neural network could be obtained.

B. Models for Conversion from GHI to GTI

Diffuse fraction and Diffuse Sky models are empirical models that are employed for conversion of GHI to GTI in the solar forecasting model chain.

1) Diffuse fraction models

There are large groups of diffuse fraction models, where the diffuse fraction only depends on the clearness index.

a) Orgill and Hollands' Model

The correlation provided by Orgill and Hollands uses four years of data gathered in Toronto, Canada [9] based on the sky cover classified as below:

$$d = (1 - 0.249k) \quad \text{For } 0 < k < 0.35 \quad (2)$$

$$d = (1.577 - 1.84k) \quad \text{For } 0.35 \leq k \leq 0.75 \quad (3)$$

$$d = 0.177 \quad \text{For } 0.75 < k \leq 1 \quad (4)$$

b) Erbs' Model

Irradiance Data from five stations in the U.S. at different latitudes were used to develop correlations [10]. The model is represented as below:

$$d = (1 - 0.09 * k) \quad \text{For } 0 < k \leq 0.22 \quad (5)$$

$$d = (0.9511 - 0.1604 * k + 4.388 * k^2 - 16.638 * k^3 + 12.336 * k^4) \quad \text{For } 0.22 < k \leq 0.8 \quad (6)$$

$$d = 0.165 \quad \text{For } 0.8 < k \leq 1 \quad (7)$$

d is the diffuse fraction

k is the clearness index

c) Chandrasekar and Kumar Model

Chandrasekar and Kumar diffuse fraction model is mentioned in the following set of equations [12].

$$k_d = 1.0086 - 0.178k \quad \text{for } k \leq 0.24 \quad (8)$$

$$k_d = 0.9686 + 0.1325k + 1.4183k^2 - 10.1860k^3 + 8.3733k^4 \quad \text{for } 0.24 < k \leq 0.8 \quad (9)$$

$$k_d = 0.197 \quad \text{for } k > 0.8 \quad (10)$$

- Where k_d = diffuse fraction, k= clearness index

2) Diffuse Sky Models

The diffuse sky models available in literature are mainly divided into two categories isotropic and anisotropic.

a) Liu and Jordan Model

The simplest models are the isotropic model which assumes that diffuse radiation is distributed uniformly over the entire sky dome and it also assumes that reflection from the

ground is isotropic. For a surface with tilt angle β , the total irradiance on the tilted surface can be obtained as follows [7] :

$$I_T = I_{hb}R_b + I_{hd} \frac{(1+\cos\beta)}{2} + I_h \rho \frac{(1-\cos\beta)}{2} \quad (11)$$

b) Hay-Davies Model

The model [8], assumes that the diffuse radiation is composed of isotropic and circumsolar components. The transmittance through atmosphere for beam radiation is defined as the anisotropy index which is used to quantify the amount of diffuse radiation coming from the circumsolar and isotropic components. It is defined as

$$A = \frac{I_{bn}}{I_{on}} \quad (12)$$

The equation for this model is described as :

$$I_T = (I_{hb} + I_{hd}A)R_b + I_{hd}(1-A) * \frac{(1+\cos\beta)}{2} * \sin^3 \frac{\beta}{2} + I_h \rho \frac{(1-\cos\beta)}{2} \quad (13)$$

I_{bn} direct-normal solar irradiance, W/m^2

I_h global horizontal solar irradiance, W/m^2

$I_{h,b}$ direct-normal component of solar irradiance on the horizontal surface, W/m^2

$I_{h,d}$ global diffuse horizontal solar irradiance, W/m^2

I_{on} direct extra terrestrial normal irradiance, W/m^2

I_T solar irradiance on the tilted surface, W/m^2

R_b variable geometric factor which is a ratio of tilted and horizontal solar beam irradiance

ρ hemispherical-hemispherical ground reflectance

β surface tilt angle from horizon

c) Klucher Model

Klucher model is described by the following set of equations [11]:

$$I_T = \frac{(I_H - I_D) * \cos(\psi)}{\sin(\alpha)} + I_D \left(\frac{1+\cos\epsilon}{2} \right) \left(1 + F \sin^3 \left(\frac{\epsilon}{2} \right) \right) (1 + F \cos^2(\psi) \sin^3(90 - \alpha)) \quad (14)$$

$$F = 1 - \left(\frac{I_D}{I_H} \right)^2 \quad (15)$$

I_T =insolation on surface tilted toward the equator at angle ϵ

I_H =total insolation received on horizontal surface

I_D =diffuse insolation received on horizontal surface

(α) = solar elevation angle

(ψ) = angle between sun direction and normal direction of tilted surface

C. Models for Conversion of Global Tilted Irradiance into DC Power

There are number of models which are used for conversion from GTI to DC power. Some of them are detailed below:

1) Huld Model

The power output in Huld Model is defined as a function of GTI and Module temperature as per the equation mentioned

below [4,5]. Based on the historic measured data of DC Power, GTI and module Temperature, the equation could be trained to find out the coefficients k_1 till k_6 .

$$P(G', T') = G' P_{STC} (1 + k_1 \ln(G') + k_2 (\ln(G'))^2 + k_3 T' + k_4 T' \ln(G') + k_5 T' (\ln(G'))^2 + k_6 T'^2) \quad (16)$$

$$G' = G/1000 (Wm^{-2}) \quad (17)$$

$$T' = T_{mod} - 25^\circ C \quad (18)$$

- $k_1, k_2, k_3, k_4, k_5, k_6$ are Huld coefficients
- G = global inclined irradiance
- T_{mod} is the module temperature

2) Beyer Model

The Beyer model is represented by the following equations. On training with historical data sets of module temperature, GTI and Measured DC Power, the values of coefficients a_1, a_2 and a_3 are estimated [6].

$$\eta_{MPP}(G, 25^\circ C) = a_1 + a_2 \cdot G + a_3 \cdot \ln(G) \quad (19)$$

$$\eta_{MPP}(G, T) = \eta_{MPP}(G, 25^\circ C) \cdot (1 + \alpha (T - 25^\circ C)) \quad (20)$$

$\eta(G, T)$ = efficiency at G , irradiance and T , module temperature

a_1, a_2, a_3 are Beyer coefficients

α = temperature coefficient

3) DC Power model based on specifications from PV Module Data Sheet

Forecasted DC power is calculated as a function of estimated tilted irradiance and module temperature as per the following equation. The parameters in the GTI to DC conversion model are chosen from the datasheet of PV Module and the design of the solar PV power plant.

$$DCPower = GTI * Number of Panels * Panel Area * Efficiency * (1 + \alpha * (temp_mod - 25)) \quad (21)$$

α = temperature coefficient of PV module.

D. DC Power to AC Power conversion Model

The conversion of DC power to AC power is based on the characteristic curve of the PV inverter. If the datasheet with efficiency values at discrete DC input levels are mentioned, the same could be used directly used in the model chain. In the absence of information from inverter datasheet, the "Schmidt and Sauer" could be used.

1) Schmidt and Sauer Model

Schmidt and Sauer model was used in the inverter modelling as per the following equations. The parameters of the Schmidt and Sauer model (P_{self} , V_{loss} , r_{loss}) will be found out by fitting the equation with input of DC and AC power measurements.

$$P_{loss} = P_{self} + V_{loss} \cdot P_{out} + r_{loss} \cdot P^2 \quad (22)$$

- P_{self} , V_{loss} , r_{loss} are inherent, magnetic, resistive loss coefficients respectively for inverter model

- Equation (23) is valid when r_{loss} is positive. Equation (24) is applicable when r_{loss} is negative.

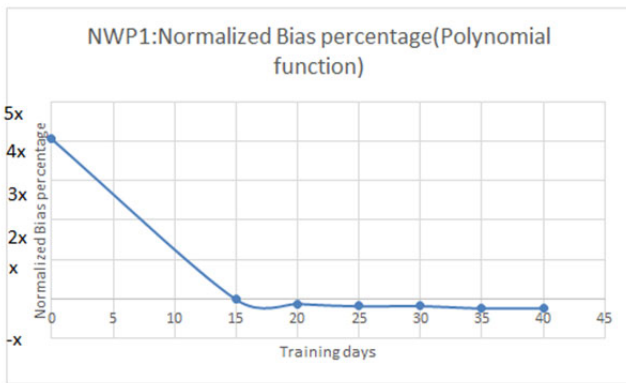


Figure 3: NMBE (in relative terms) vs training days for NWP1 of Polynomial Function bias correction method

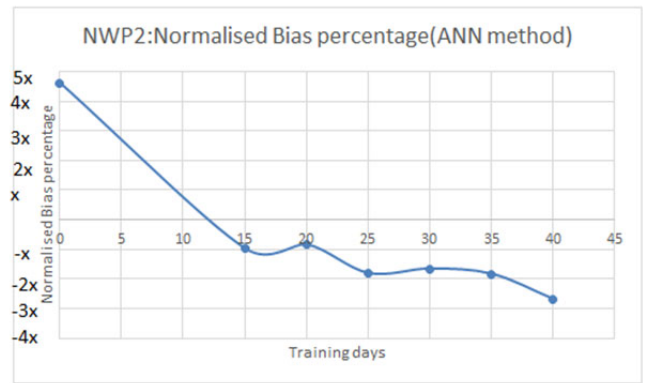


Figure 6: NMBE (in relative terms) vs training days for NWP2 of ANN bias correction method

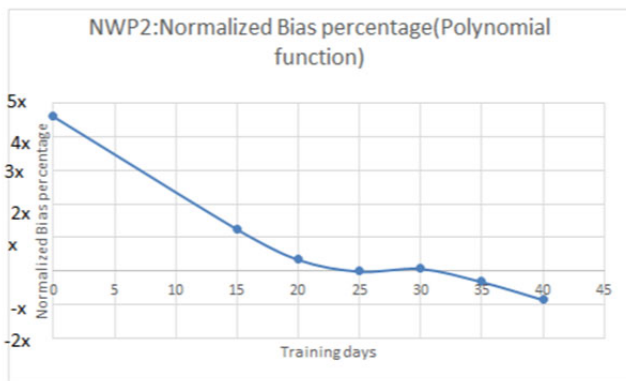


Figure 4: NMBE (in relative terms) vs training days for NWP2 of Polynomial Function bias correction method

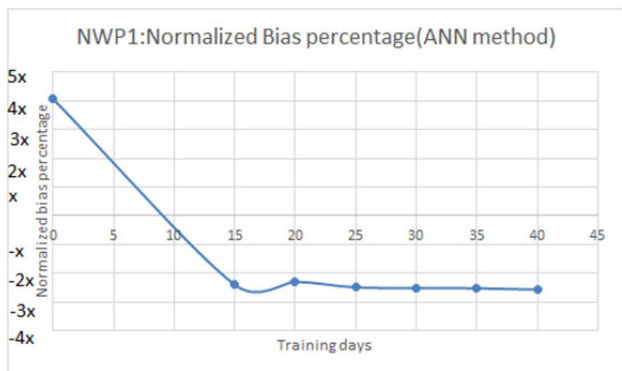


Figure 5: NMBE (in relative terms) vs training days for NWP1 of ANN bias correction method

Diffuse fraction model of “Chandrasekar and Kumar” and Tilt Conversion model of “Klucher” was employed in the model chain. The effectiveness of two GTI to DC models (Huld and Beyer) were cross compared. The equations of the models were shown in the previous section. Since DC power information was not available, it was estimated by reverse-calculating from Schmidt-Sauer model. Corresponding coefficients for Huld and Beyer model was calculated by fitting the equations with Module temperature, GTI measurements and estimated DC power. The Schmidt and Sauer coefficients, were calculated for different power plant where DC and AC power measurements were available. The same set of coefficients were used in this specific forecasting model chain. Combination of AC power were also performed. It was performed by the following formula:

$$ACPowerFcst_{Combi} = a1 * ACPowerFcst_{NCMRWF} + a2 * ACPowerFcst_{ECMWF}$$

The coefficient of the combination equation was trained on 15 days sliding window approach. The validation period for AC power validation is between 1st May 2019 till 16th June 2019. The results for the validation of AC power forecast with both the NWP's and the combination is shown in Table 2. The performance of NWP1 is better compared to NWP2 based model chain. The accuracy of combination of NWP's is better compared to individual NWP performance. The weightage of different NWP's are different for the validation days. Relative performance of the NWP's are varying in the validation time period. The Scatter plots of measured and forecast (combination) value is represented in Figures 7 and 8.

Table 2: The results for validation of AC power forecasts with individual NWP's and Combination

MODEL	NCMRWF AC FORECAST			ECMWF AC FORECAST			COMBINATION OF NCMRWF & ECMWF AT POWER END		
	nRM SE (%)	nMAE (%)	nMBE (%)	nRM SE (%)	nMAE (%)	nMBE (%)	nRM SE (%)	nMAE (%)	nMBE (%)
BEYER	X1	Y1	Z1	0.908 X1	1.088 Y1	-0.31 4Z1	0.861 X1	0.955 Y1	1.04 Z1
HULD	1.014 X1	1.13 Y1	-1.06 4Z1	0.895 X1	1.025 Y1	0.23 2Z1	0.866 X1	0.955 Y1	1.17 Z1

good accuracy. Step by step scientific approach was followed in development of the model.

Some of the steps which would aid in improvement of model performance is listed in the following:

- Addition of aerosol information in NWP model by the meteorological agencies.
- Bias correction coefficients calculated on seasonal basis.
- Testng with advanced diffuse fraction models.
- Analyzing the NWP model performance based on weather classes defined by meteorological agencies and development of corresponding combination coefficients.

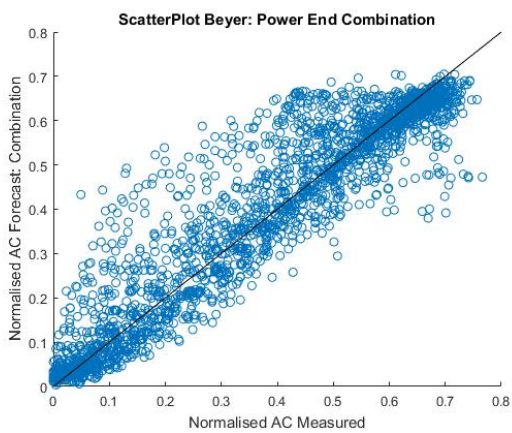


Figure 7: The Scatter plot of Combined AC power forecast and Measured AC power (GTI to DC model: Beyer)

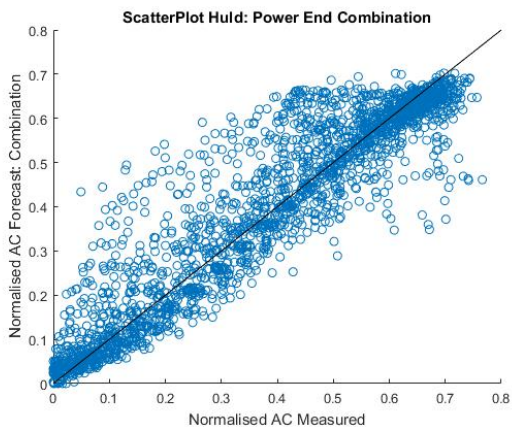


Figure 8: The Scatter plot of Combined AC power forecast and Measured AC power (GTI to DC model: Huld)

Its very important to receive all the possible data with highest quality for optimum performance of the model. In the current work, DC power data (dynamic), the exact period in which tilt angle is changing (manual seasonal tilt), were not received from the plant operator. The data from Availability Based Tariff meters is more accurate. However, this data is being received only in the interval of 15 days. The data from SCADA requires a lot of cleaning. It was also observed that pyranometers and other sensors are not being maintained well. Even the highest quality instruments not properly maintained, will result in poor data which will affect the model performance. Diffuse Horizontal radiation are not measured by Power plant operators. Availability of the above data will help is development of site-specific diffuse fraction models. It is expected that as more quality data and implementation of advanced modelling approaches, the developed indigenous forecasting model chain will attain international standards.

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V DISCUSSION AND CONCLUSION

Indigenous forecasting model was setup to forecast the power generation of group of solar power plants. Maximum datasets from Indian sources has been employed in the exercise. The forecasting system was evaluated to have

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