
Activities of the Joint Working Group CIGRE C4/C6.35/CIREN: Modelling and Dynamic Performance of Inverter Based Generation in Power System Transmission and Distribution Studies

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On behalf of: JWG CIGRE C4/C6.35/CIREN

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Overview of CIGRE JWG C4-C6.35/CIRED

WG Composition:

- WG Co-Conveners: Koji Yamashita and Herwig Renner
- Number of full members: 45
- Number of corresponding members: 21
 - Number of countries represented: 23
 - Number of members from industry: 38
 - Number of members from university/R&D: 28

WG Timeline:

- Start date: 2013/10
- End of WG activities: 2017/03

Overview of CIGRE JWG C4-C6.35/CIRED

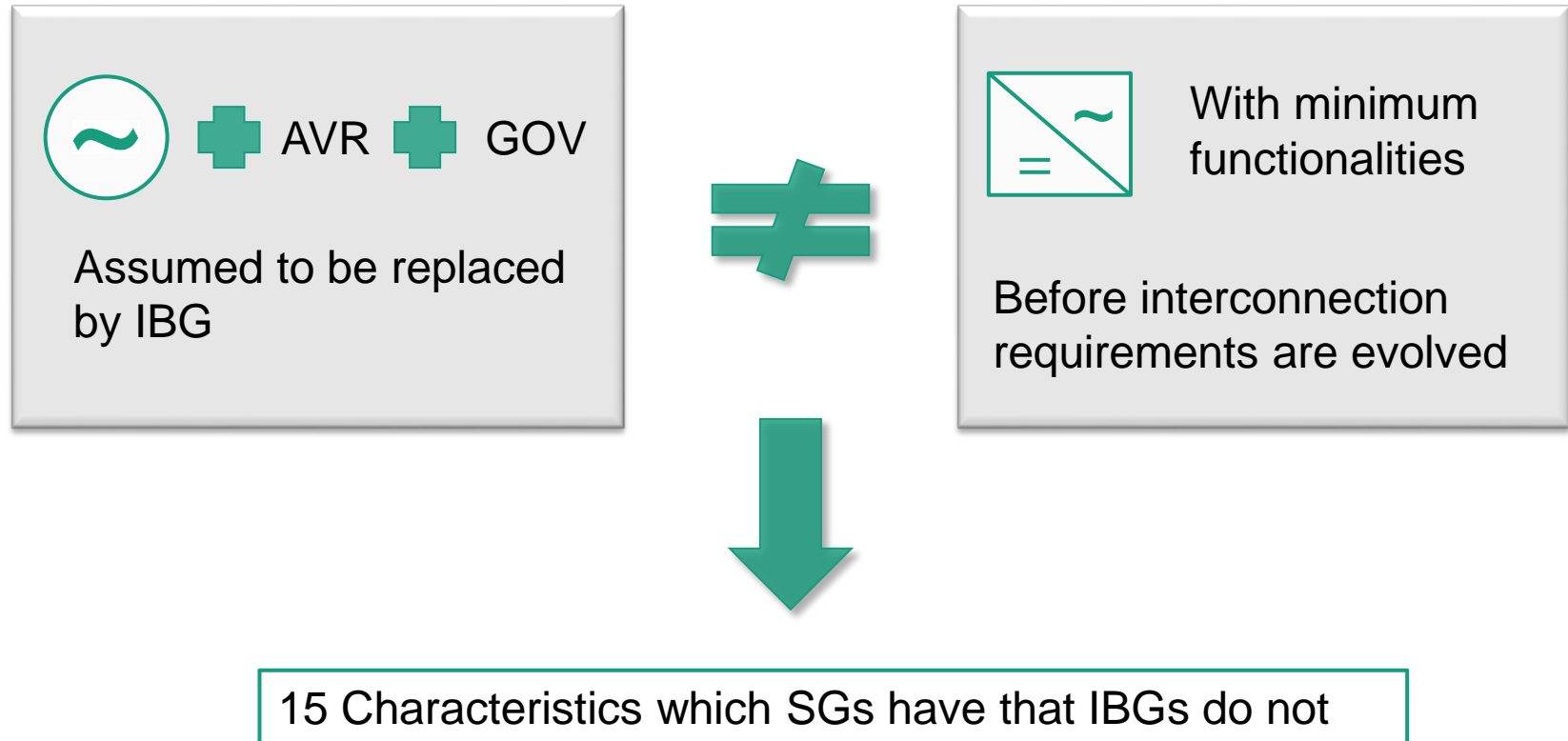
Recent Activities:

- CIRED Tutorial was held in Glasgow, Scotland on 2017/06.
- IEEE Powertech 2017 Special Session was held in Manchester, United Kingdom on 2017/06
- Extra meeting for U.S. members was held in Chicago on 2017/07 (during IEEE GM 2017).
- Native language check of the technical brochure has finished in 2017/08.
- 2 TBs are expected to be submitted to CIGRE/CIRED by the end of 2017.

Other Items:

- 2 TBs will be published by no later than end of Jan. 2018.

1. Comparison with Synchronous Generators





With minimum functionalities

■ Major differences between IBG and SG are:

- Contribution to Inertia
- Fault Current Provision
- Synchronization Capability
- Constant Internal Voltage Source (grid forming capability)



These capabilities are very hard to achieve with IBGs in an equivalent way as a SG.

Rotating mass/inertia

Frequency response capability

Limited frequency sensitive

- To emulate this capability the IBG needs to increase or decrease the active power output.
- Decreasing P is easy.

- PVs can easily change the output as **there is no such limitation** of the “limited frequency sensitive mode” for PVs.

- Synthetic inertia **cannot be considered** completely equivalent to the inertia provided by SG.
- Measuring devices and control **introduce delays.**

Advanced capability / Advanced capability of IBG

..., depending on: Prime mover, operating point, storage device and direction of frequency deviation

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...s (prime mover dependent)

	Conventional SG	IBG with minimum functionalities	Advanced capability / Advanced feasibility of IBG
Constant voltage source		<ul style="list-style-type: none"> The IBGs themselves can change the reactive power output through the oversized inverter and/or through the reduction of active power output. The IBGs themselves can change the reactive power output through the oversized inverter and/or through the reduction of active power output. 	but in order to have a constant voltage following oversizing of the inverter necessary
Grid voltage support (Steady state)			(large-scale IBGs only)
Reactive power support (V-Q steady state)			reactive power compensators (shunt reactor, SVC, ...)
Reactive power support (reactive current control during incidents)			according to PQ capability
			usually during faults IBGs are able to provide a reactive current injection with some delay.

	Conventional SG	IBG with minimum functionalities	Advanced capability / Advanced feasibility of IBG
Synchronization (torque) capability	Yes	No	Yes (but almost infeasible)
Damping torque capability (power oscillation damping capability)	Yes, damper		Yes, POD functionality
FRT capability			prime mover dependent)

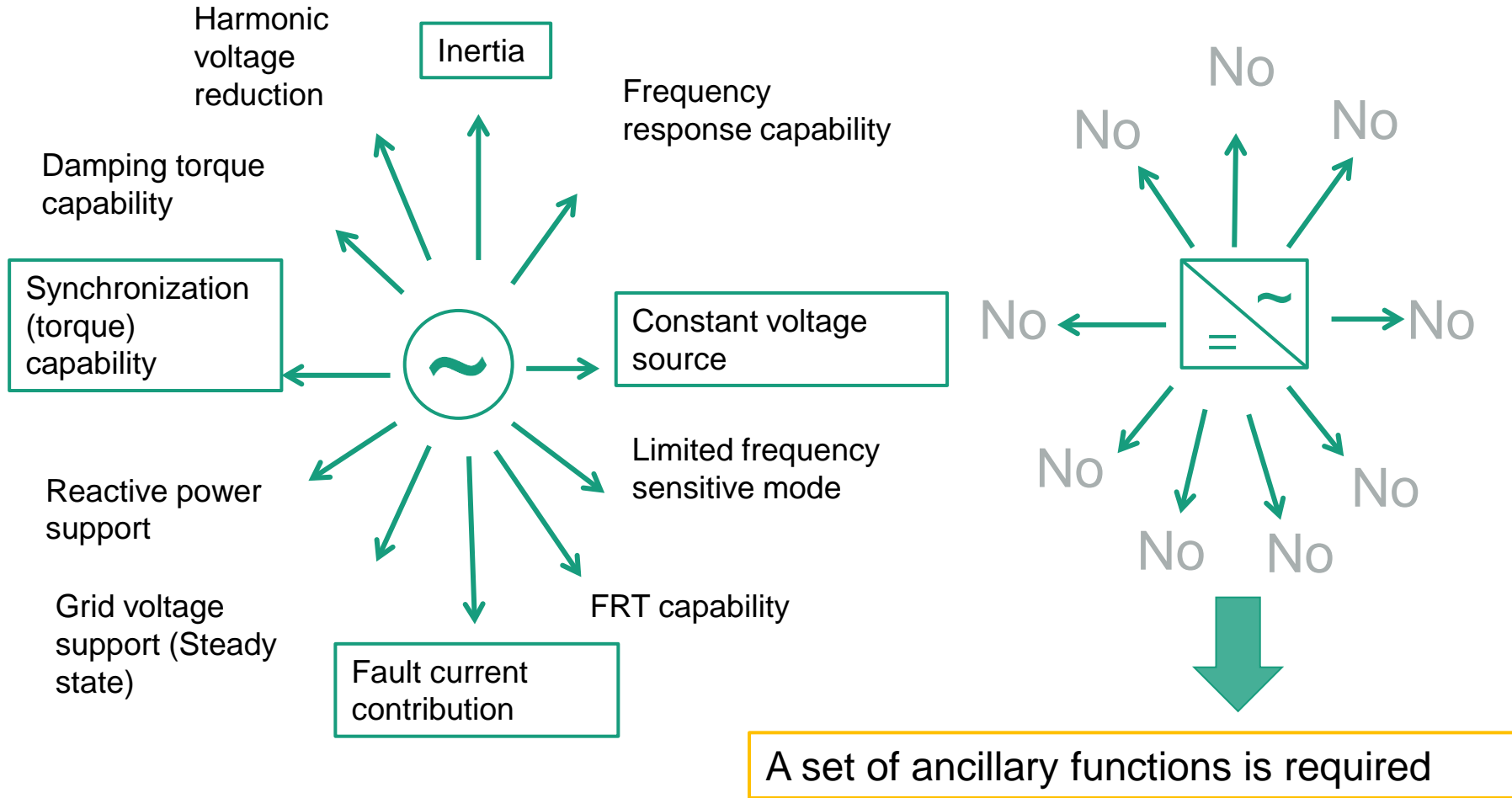
- The IBGs might be required to have the synchronizing torque capability in the future.
- It is very difficult to achieve because the angle difference needs to be observed **without time delay**.

mitigating Power Swing Oscillations.

	Conventional SG	IBG with minimum functionalities	Advanced capability / Advanced feasibility of IBG
Harmonic emission	No	Yes, supra-harmonics	-
Harmonic voltage reduction	Yes, for low order harmonics	No	Yes, if active filter algorithms are implemented
Fault current contribution	Yes	No	Yes, but contribution is limited to around 1 p.u.
Control response capability			enter itself fast, possible limitations due to measurement delay
Overload capability (up to few seconds)			but significant oversized IBGs are required.

- SGs provide a rather low impedance path for harmonic currents and thus tend to reduce harmonic voltages.
- IBGs equipped with algorithms in the control system are able to **act as active filter**, reducing (low order) harmonic current and therefore, voltages.

Inherent Characteristics





- SGs may be replaced by IBGs. Hence, functionalities which the SGs have, **will be lost and the system stability may be affected.**
- In order to cope with this, such functionalities have been required by the IBGs through **updating of Grid Codes.**

2. Ancillary functions

- Because of the flexibility of the inverter control design, IBGs may be required either, from the technical Standards and/or from Grid Codes, to **provide some additional capabilities for grid support**.
- The following tables show the most relevant requirements of capabilities for IBGs from:
 - European commission - **EU Regulation 2016/631** establishing network code requirements for grid connection of generators (NC-RfG).
 - **The IEEE 1547** - Standard for Interconnecting Distributed Resources with Electric Power Systems .

2. Ancillary functions

Requirement	EU 2016/631	IEEE 1547	IEEE 1547 (Future)
P(f) (over/under)	x		x
Voltage Control by means of Reactive Power (Q(V))	x	(x)	x
Voltage Control by means of Active Power (P(V))			x
Synthetic Inertia	(x)		
ROCOF Immunity	x		x
Voltage phase angle jump immunity			x
LVRT & HVRT	x (LVRT only)	(x)	x
Anti-islanding Detection Methods	x (ROCOF)	x	x

x means one or more classes/categories of the IBGs that are required.

() denotes a non-mandatory requirement.

2. Ancillary functions

Requirement	EU 2016/631	IEEE 1547	IEEE 1547 (Future)
Dynamic Voltage Support during faults and voltage dips	(x)		(x)
Power Oscillation Damping	(x)		
Black Start Capability	(x)		(x)
Capability of Islanding Operation	x		(x)
Automatic Disconnection with Abnormal Voltage	x	x	x
Automatic Connection with Active Power Recovery Speed	x		x
Constant Power at Low Voltage	x		x
Constant Power at Low Frequency	x		x

x means one or more classes/categories of the IBGs that are required.

() denotes a non-mandatory requirement.

3. Inverter protection

- Inverter Protection may be distinguished into
 - Internal Protection (DC Protection)
 - Internal Protection (AC Protection)
 - Internal Protection (Protection Purpose Control)
 - External Protection (Interface Protection Systems)

“Limitation of inverter current’s

Required to serve a different purpose and consider the network. **Monitoring the network**, not the inverter.

Loss of Mains Protection (LOM)
UFR/OFR, UVR/OVR

1	Reduction of maximum inverter current limit
2	Limitation of inverter current
3	Limitation of current
4	DC Overvoltage Protection
5	Overvoltage/Undervoltage Protection
6	Overfrequency/Underfrequency Protection
7	Protection for Detecting Balance
8	Protection for Detecting Unbalanced Short-Circuit Fault
9	Protection for Detecting Single-line-to-ground Fault
10	ROCOF tripping: monitoring the power frequency variation rate and disconnecting the inverter when it reaches a certain limit [Hz/s]
11	Vector jump
12	Transfer trip
13	Anti-islanding active detection method

Compared to the synchronous generators, IBGs are more likely to be disconnected due to the high sensitivity inverter protections.

Because the operation of the inverter protection could result in the disconnection of the IBG, the inverter protection models play an important role for most of the dynamic stability analysis.

3. Conclusions

- The major differences between conventional SGs and IBGs are:
 - The inertia
 - The fault current provision
 - The synchronization capability
 - The fixed internal voltage source.

- Those four characteristics are provided by synchronous generators. However, **they are not easily provided by IBGs.**

3. Conclusions

- On the other hand, many of the characteristics such as the frequency control capability and the reactive power control capability **can be provided by IBGs**.
- Compared to the synchronous generators, **IBGs are more likely to be disconnected** due to the high sensitivity inverter protections.
- Because the operation of the inverter protection could result in the disconnection of the IBG, **the inverter protection models play an important role for most of the dynamic stability analysis**.

3. Conclusions

List of Functionalities

Control

Protection

Capability

Comparison of
Characteristics
IBG vs SG

Evolution of Grid
Code Requiring
Ancillary Functions

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Fraunhofer IWES - Business Field Grid Planning and Operation

- Techno-economic studies for analyzing, planning, operation, control, stability of power systems
- Automated Planning Tools (e.g. pandapower <http://www.uni-kassel.de/go/pandapower>)
- Operational Tools (algorithms for ancillary services, hardware/software platform for pilot systems)
- (Co-Simulation) Test Platforms for operational solutions (www.opsim.net)
- Multi-Energy System Planning and Operation (Power, Heat, Gas)
- Microgrid/ Hybrid System Test Bench and PHIL Tests

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Department Energy Management and Power System Operation - e²n

- Development of models, methods, algorithms and tools for analysis, operation and control, and design of the future decentralized power system with high share of renewable energies. e.g. pandapower
- Multi-Objective/Perspective/Level Optimisation of the power system
- Simulation of the power system over time scales and system levels.
- Resilient Control Design incl. power system stability, network restoration, microgrid structures